

## Linear Programming

### Definitions and Properties (cont.)

An LP is in the **augmented form** if all the variables are nonnegative and all the functional constraints are equations (built with **slack/surplus variables**, if necessary).

An **augmented solution** is a solution for an LP problem in the augmented form.

**Property 5:** Every LP problem can be rewritten as an equivalent problem in the maximisation augmented form.

**Proof** (writing an LP problem as a maximisation augmented form problem)

$$(i) \quad \text{Min } Z = \sum_{j=1}^n c_j x_j \quad \rightarrow \quad \text{Max}(-Z) = \sum_{j=1}^n (-c_j) x_j \quad (\text{Min } Z = -\text{Max}(-Z))$$

$$(ii) \quad \text{'}\leq\text{' constraint: } \sum_{j=1}^n a_{ij} x_j \leq b_i \Leftrightarrow \sum_{j=1}^n a_{ij} x_j + x_{n+i} = b_i \wedge x_{n+i} \geq 0$$

$$(iii) \quad \text{'}\geq\text{' constraint: } \sum_{j=1}^n a_{kj} x_j \geq b_k \Leftrightarrow \sum_{j=1}^n a_{kj} x_j - x_{n+k} = b_k \wedge x_{n+k} \geq 0$$

$$(iv) \quad \text{nonpositive variable: } x_j \leq 0 \Leftrightarrow x'_j = -x_j \geq 0$$

$$(v) \quad \text{free variable: } x_j \text{ free} \Rightarrow x_j = x'_j - x''_j, \text{ with } \begin{cases} x'_j = \text{Max}\{0; x_j\} \geq 0 \\ x''_j = \text{Max}\{0; -x_j\} \geq 0 \end{cases}$$

Consider a problem with  $m$  equations and  $\ell$  ( $> m$ ) nonnegative variables. A **basic feasible solution (BFS)** is a solution for the problem that is obtained by setting  $\ell - m$  variables equal to zero – **nonbasic variables (NBV)** – and solving the resulting system for the remaining  $m$  variables – **basic variables (BV)** – in case this system is feasible and determined, and with a nonnegative solution.

Each BFS is associated with a single corner point of the feasible region, named **corner point feasible solution (CPF)**. Each CPF is associated with at least one BFS.

Two BFSs are **adjacent** if all but one of their basic variables are the same (consequently, the respective sets of nonbasic variables also differ by one single variable).

## Solving LP problems

### Simplex algorithm (George Dantzig, 1947)

Let us consider an LP problem in the **standard form**<sup>(1)</sup> and with nonnegative right-hand-sides (RHS).

**Step 1:** write the problem in the augmented form

**Step 2:** determine a BFS  
set  $k \leftarrow 1$

{Iteration  $k$ }

**Step 3:** if the BFS is optimal then **stop**  
otherwise, continue

**Step 4:** apply the “entering criterion” to select  $x_p$ , the new BV  
apply the “leaving criterion”  
if not possible then **stop** (unbounded OF)  
otherwise, let  $x_r$  be the new NBV

**Step 5:** update the new Simplex tableau thus building the new BFS (exchange variables  $x_p$  and  $x_r$ )  
set  $k \leftarrow k + 1$   
go to **step 3**

#### Notes:

**entering criterion** – select among the variables with negative coefficient at the OF row, the one with the most negative coefficient (variable  $x_p$ ).

**leaving criterion** – in order to guarantee the feasibility of the new BFS, calculate the minimum of the ratios of the RHS and the positive coefficients of the entering column (variable  $x_p$ ). The variable associated with that minimum ( $x_r$ ) will be nonbasic in the new solution.

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<sup>(1)</sup> The Simplex algorithm can be adapted to any LP problem.